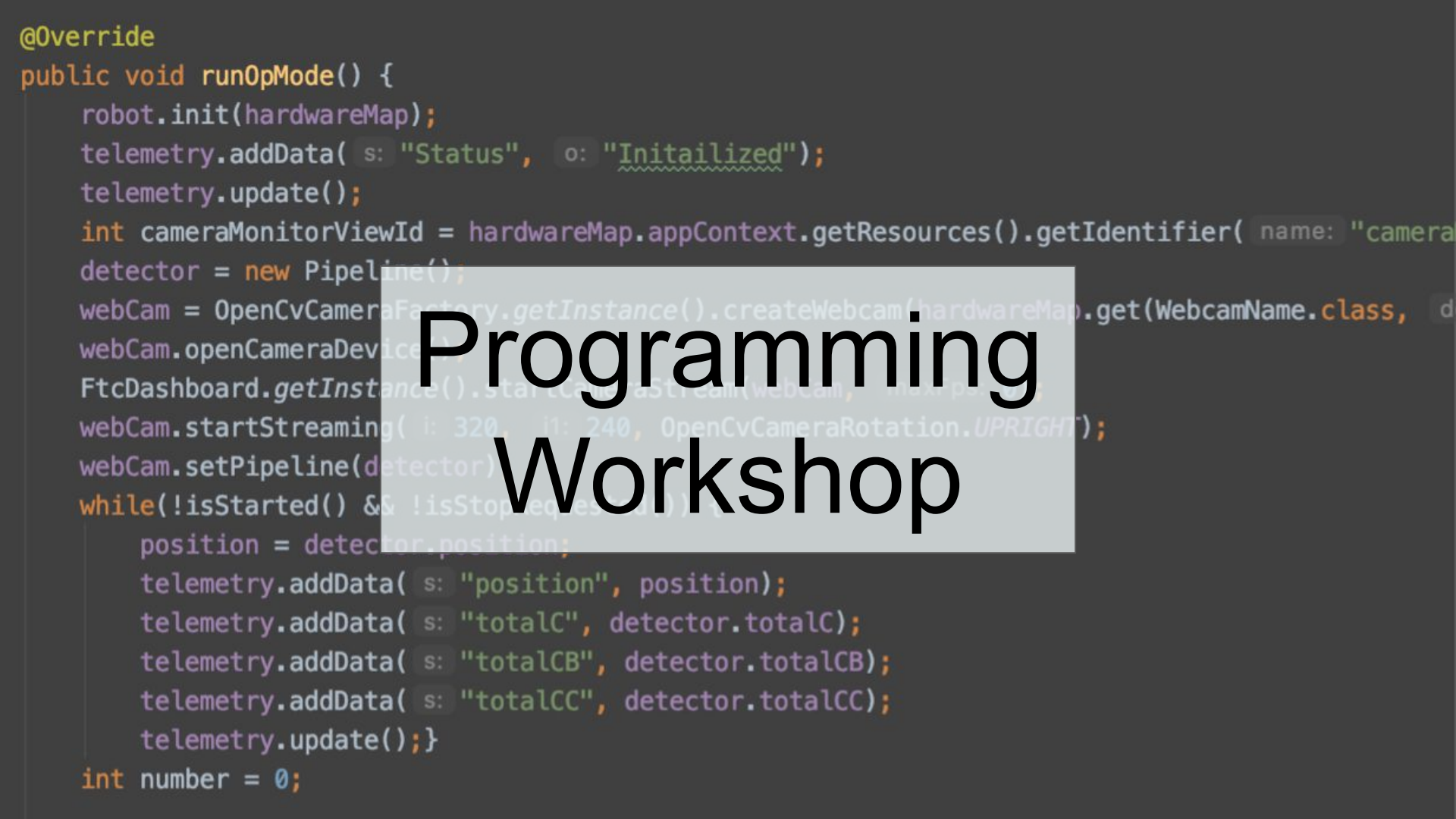

@Override
public void runOpMode() {
robot.init(hardwareMap);
telemetry.addData(s: "Status", o: "Initailized");
telemetry.update();
int cameraMonitorViewId = hardwareMap.appContext.getResources().getIdentifier(name: "camera
detector = new Pipeline();
webCam = OpenCvCameraFactory.getInstance().createWebcam(hardwareMap.get(WebcamName.class,
webCam.openCameraDevice
FtcDashboard.getInstance().
webCam.startStreaming(i: 320, i1: 240, OpenCvCameraRotation.UPRIGHT);
webCam.setPipeline(detector);
while(!isStarted() && !isStopRequested()) {
position = detector.position;
telemetry.addData(s: "position", position);
telemetry.addData(s: "totalC", detector.totalC);
telemetry.addData(s: "totalCB", detector.totalCB);
telemetry.addData(s: "totalCC", detector.totalCC);
telemetry.update();}
int number = 0;
Programming
Workshop

What is programming?

- Process of creating a set of instructions that tell a computer how to perform a task
- Basically, what makes the robot function

What is a programming language?

- Any of various high-level languages used for computer programs
- Ex. Java, C++, Python

What is Java?

- An object-oriented programming language that produces software for multiple platforms

How to learn Java?

- Free Online Resources
  - Codecademy
- AP Computer Science A

What is an SDK?

- Stands for Software Development Kit
- Brings together group of tools that enable programming of mobile applications and robots
- Allows pre-programmed processes to call on
  - Ex. Java’s Math class

What is the FTC SDK?

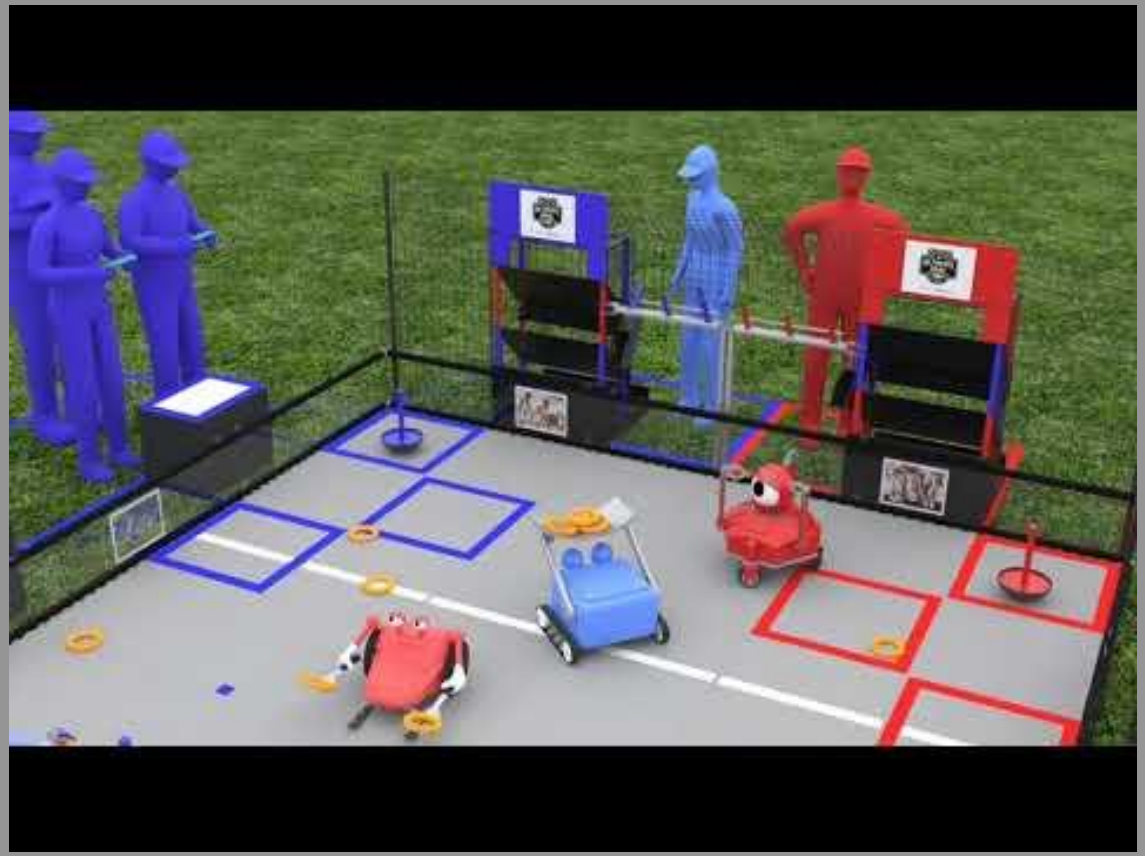
- SDK design specifically for FTC programming
- Provides specific programmed processes
  - Ex. Calling robot.setPower(0)
- Link will be provided as soon as released

Aspects of FTC Competition:

- Two periods with different goals
  - Autonomous - First 30 seconds
  - TeleOp - Remaining 2:00 minutes
    - Endgame - Last 30 seconds of TeleOp

FIRST TECH CHALLENGE

Autonomous Period

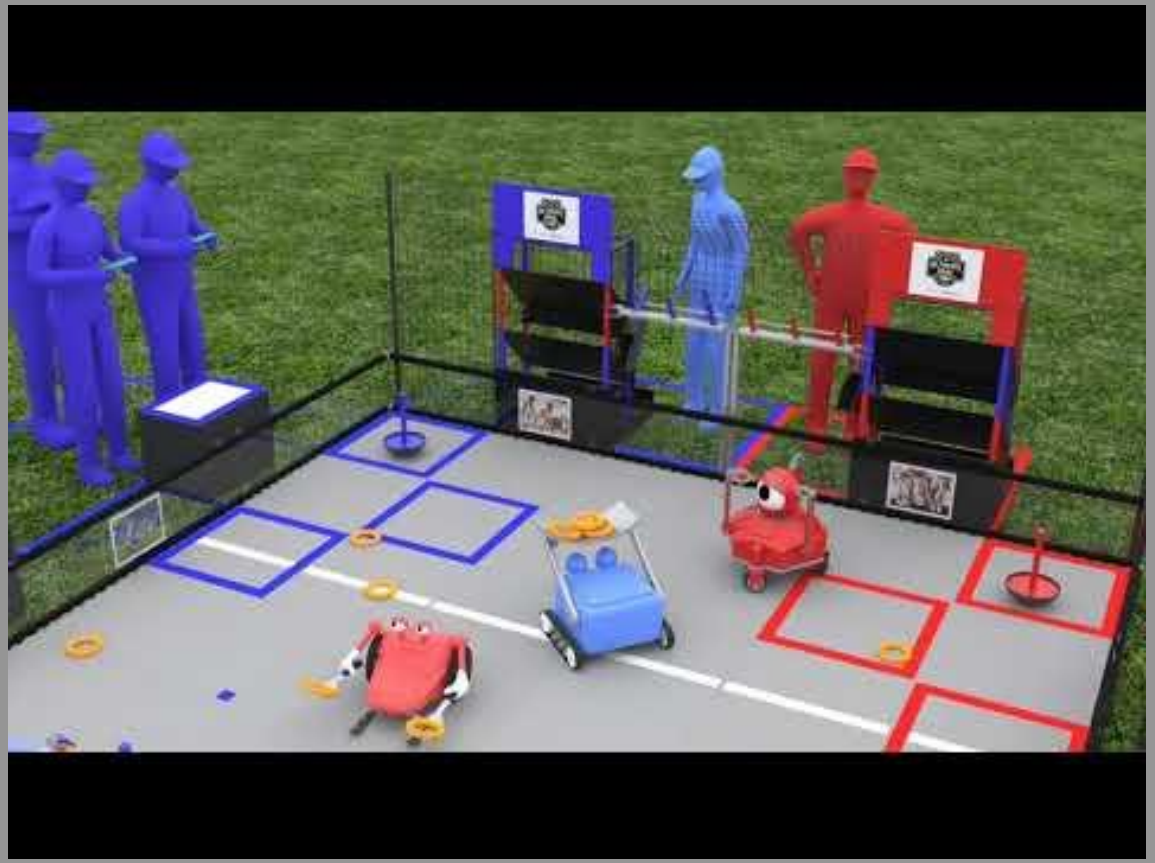


Autonomous Period

- Only pre-programmed instructions
  - Drivers do not control robot
- Different goals than in other parts of competition

FIRST®
TECH
CHALLENGE

TeleOp Period



TeleOp Period

- Driver controlled
- Two Driver
  - Primary Driver: Controls driving
  - Secondary Driver: Controls subsystems

FIRST TECH CHALLENGE

TeleOp Period

Sensors

- Gyroscope
- Camera
- Color Sensor
- Touch Sensor

Gyroscope

- Provides accurate angles
- Recommended for precision turning
- Built into Control Hub

Camera

- Used for computer vision
  - Allows to detect different colors, darknesses, etc.
- Detect starter of rings

Color Sensor

- Detect colors
- Determine whether something passes
  - Ex. Rings going through intake
- Sometimes distance sensor
- Driver Automations

Touch Sensor

- Determine contact between two surfaces
- Driver Automations

Motors vs. Servos

- Motors
  - Work with time and encoders
  - Usually used with wheels
- Servos
  - Use positions to complete motions
  - Work only with time or waiting for completion

Movement Tracking

- Time Based
- Encoders
- Odometry

Time Based

- Uses time (seconds, minutes) to control motion
- Advantages:
  - Travel a distance for a specified time
- Disadvantages:
  - Does not insure for accurate distance
    - Motor/servo only runs as long as programmed for
  - Does not account for slippage

Encoders

- Plug into motors
- Advantages:
  - Travel precise distances
- Disadvantages:
  - Does not account for slippage
  - Slippage increases as robot travels faster

Odometry

- Uses vertical and horizontal wheels to calculate where to move
- Advantages:
  - Accounts for slippage
  - Travel accurate distances
  - Allows robot to plot own path
- Disadvantages:
  - More difficult to program
  - Wheels difficult to align

Programming in Action

```
@Override
public void runOpMode() {
    robot.init(hardwareMap);
    telemetry.addData( s: "Status",  o: "Initailized");
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    detector = new Pipeline();
    webCam = OpenCvCameraFactory.getInstance().createWebcam(hardwareMap.get(WebcamName.class,
    webCam.openCameraDevice();
    FtcDashboard.getInstance()
    webCam.startStreaming(
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    while(!isStarted() && !isStopRequested()) {
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        telemetry.addData( s: "totalCC", detector.totalCC);
        telemetry.update();}
    int number = 0;
```

Questions?

Important Programming Links

Android Studio

Codecademy

This Presentation

Club Announcements

Robotics Application Form

Insurance Website

Club Communication

Remind
Text @phuhsro to 810-10

Discord